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#### From the INTERNATIONAL BUREAU

**PCT** 

NOTIFICATION OF ELECTION

(PCT Rule 61.2)

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Date of mailing:

18 January 2001 (18.01.01)

International application No.:

PCT/PL00/00030

International filing date:

19 April 2000 (19.04.00)

Applicant:

OLĘ DZKI, Wiesł aw, Julian

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		02 October 2000 (02	.10.00)	
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## **PCT**

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## INTERNATIONAL PRELIMINARY EXAMINATION REPORT

(PCT Article 36 and Rule 70)

8

Applicant's or agent's file reference		San Notification of Transmitted
J.	FOR FURTHER ACTION	See Notification of Transmittal of International Preliminary Examination Report (Form PCT/IPEA/416)
International application No.	International filing date (day/month/y	year) Priority date (day/month/year)
PCT/PL00/00030	19/04/2000	12/07/1999
International Patent Classification (IPC B60G17/02	) or national classification and IPC	
Applicant		
OLEDZKI, Wieslaw, Julian		
This international preliminary and is transmitted to the applic	examination report has been prepared b	by this International Preliminary Examining Authori
and is transmitted to the applic	ant according to Article 36.	5
2. This REPORT consists of a to	tal of 4 sheets, including this cover she	et.
☑ This report is also accomp	anied by ANNEXES, i.e. sheets of the	description, claims and/or drawings which have
	on do the Administrative instructions	s under the PCT).
These annexes consist of a tot	al of 4 sheets.	
3. This report contains indications	relating to the following items:	
l ⊠ Basis of the report	·	
II Priority		
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IV   Lack of unity of inve	ention	ive step and industrial applicability
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VI ☐ Certain documents		•
VII ☐ Certain defects in the VIII ☐ Certain observation	e international application	
VIII   Certain observation	s on the international application	
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D-80298 Munich Tel. +49 89 2399 - 0 Tx: 523	Roberts, D	
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#### INTERNATIONAL PRELIMINARY **EXAMINATION REPORT**

International application No. PCT/PL00/00030

l. I	Basis of the report				
á	the receiving Citice i	ements of the internationa In response to an invitation I to this report since they do	Under Article 17 arc	roforrod to in this	
3	3-9	as originally filed			
1	,2	_ as received on	18/09/2001-	-with-letter-of-	10/09/2001
c	Claims, No.:				
1	-9	as received on	18/09/2001	with letter of	10/09/2001
D	rawings, sheets:				
1,	/8-8/8	as originally filed			
	nese elements were	international application wavailable or furnished to the	is Authority in the fo	llowing language:	, which is:
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	the language of a 55.2 and/or 55.3).	ublication of the internatior translation furnished for th	e purposes of intern	r ние 48.3(b)). ational preliminary	examination (under Rule
3. Wi int	ith regard to any <b>nuc</b> ernational prelimina	eleotide and/or amino aci y examination was carried	d sequence disclose out on the basis of	ed in the internation the sequence listin	nal application, the
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	The statement that	the information recorded i	n computer readable	e form is identical t	to the written sequence

4. The amendments have resulted in the cancellation of:

listing has been furnished.

## INTERNATIONAL PRELIMINARY EXAMINATION REPORT

International application No. PCT/PL00/00030

		the description,	pages:		
		the claims,	Nos.:		
		the drawings,	sheets:		
5.		This report has been considered to go bey	establish ond the c	ed as if (s lisclosure	some of) the amendments had not been made, since they have been as filed (Rule 70.2(c)):
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6.	Add	itional observations, if	necessa	ry:	
V.	Rea:	soned statement und tions and explanation	der Articl	e 35(2) w orting suc	rith regard to novelty, inventive step or industrial applicability;
1.		ement			
	Nove	elty (N)	Yes: No:	Claims Claims	1-9
	Inver	ntive step (IS)	Yes: No:	Claims Claims	1-9
	Indus	strial applicability (IA)	Yes: No:	Claims Claims	1-9
2.	Citati	ions and explanations			

see separate sheet

### VII. Certain defects in the international application

The following defects in the form or contents of the international application have been noted: see separate sheet

## INTERNATIONAL PRELIMINARY International application No. PCT/PL00/00030 EXAMINATION REPORT - SEPARATE SHEET

#### 1. Reasoned Statement (V)

- 1.1 The present invention relates to a vehicle suspension system comprising a spring and a four-link mechanism and having a non-linear dependence of deformation of the spring on the vehicle wheel movement. Such a system corresponding to the preamble of claim 1 is known, for example, from WO-A-96/11815.
- 1.2 The object of the present invention to provide an improved suspension system having a compact, simple and robust structure able to cope with large loads.
- 1.3 The above object is achieved by means of the characterising features of claim 1, which are neither known from nor rendered obvious by the available prior art.

#### 2. Certain Defects (VII)

2.1 The application contains the following obvious error (see Guidelines VI-7.14): The word "sliders" is missing in claim 9, line 4 between "corresponding" and "(D1)".

::

### - Vehicle suspension system, particularly for road and off-road vehicles

The present invention relates to a vehicle suspension system, particularly for road and off-road vehicles, such as trucks, buses and military vehicles, including tanks, and first of all-for those vehicles whose weight and dynamical loads vary within a broad range during the operating process.

The main function of vehicle suspension is to reduce vibrations transferred to a vehicle body by vehicle wheels. The suspension is a set of elements connecting the vehicle wheels with the vehicle frame or body. Suspensions of automotive vehicles are fitted with steel springs such as leaf springs, coil springs, torsion bars, as well as solid rubber elements and pneumatic springs and hydro-pneumatic elements.

Leaf springs are made of elastic steel flat bars. The leaf spring, supported in the middle and loaded on both ends, is subject to deformation and simultaneously works against the forces of elasticity.

Coil springs are made of steel spring wire. They are lighter and easier to assemble than leaf springs but unable to transfer side forces, hence additional elements are necessary to hold the vehicle axle.

Torsion bars are steel springs made in the form of rod, tube or flat bar pack, one end of which is anchored e.g. in a vehicle frame while the other one is twisted by an arm of a vehicle wheel.

Pneumatic springs are built in the form of two or three-fold bellow manufactured of synthetic rubber reinforced with cord plait and tightened in metallic holders. Pneumatic springs work utilizing pressure of compressed air contained therein. They are used in buses and trucks as well as in off road vehicles. There are also hydro-pneumatic suspensions, in which the elastic medium is a compressed gas contained in a chamber.

Further compression of the gas results from the action of a piston, which follows the movement of a vehicle wheel.

The spring rate of steel springs is, in general, constant. Thus the damping characteristic of most prior-art vehicle suspension systems using such a spring is linear or nearly linear, which is their major disadvantage. Some of steel springs, e.g. coil springs, can be made progressive, however damping characteristic of vehicle suspension using such springs cannot be freely shaped and remains remarkably inferior to that of the air spring.

Some unconventional vehicle suspension systems providing non-linear damping characteristic and means for adjusting it are known from prior art. For example the International Publication WO-A-96 11815 of the International Application PCT/CA 95/00570 discloses a suspension system, in which the suspension arm rotates roller carriers, the rollers contained therein follows cam surfaces, which in turn force a spring supports to move axially and to compress the spring. The US patent No. 3,157,394 granted to Mr. O. K. Kelley in 1964 provides another example of suspension with a cam mechanism, a number of in turn actuated Belleville springs and non-linear non-differentiable characteristic. However non-linearity of damping characteristic of these suspensions is achieved by engaging springs through a cam mechanism, and means for adjusting the characteristic are shape of the cam, its position relative other elements of the suspension mechanism and nuts to regulate the initial length of the spring. Consequently, these suspensions are exceedingly complicated, of questionable durability and reliability, unable to cope with large loads, and means for adjusting damping characteristic of them are completely unsatisfactory.

A vehicle suspension, according to the present invention, is a purely mechanical device. Non-linearity of its damping characteristic and means for adjusting it to specific requirements is derived directly from the kinetic of the four bar mechanism. It contains no foreign ad hoc incorporated parts e.g. cams and features a compact and robust structure. In fact the structure of the mechanism of the suspension according to the present invention is the strongest possible as its moving parts occupy the whole internal space of its body. Thus it can cope with large loads and the capacity/weight ratio would be better than that of all kinds of known suspensions. It uses only standard springs, while it provides a damping characteristic, which betters that of hydro-pneumatic suspensions. Moreover the construction of the suspension, according to the invention, enables its characteristic to be freely chosen through the choice of the geometric parameters of the mechanisms comprised therein.

The manufacturing technology of the suspension according to the invention is simple and inexpensive. Moreover, the suspension provides the possibility of the relative position between elements connecting the suspension unit with vehicle wheels and a spring to be freely adjusted.

The invention solves the problem of constructing a vehicle suspension of non-linear characteristic using springs of linear characteristic. By non-linear characteristic is meant non-linear and differentiable dependence of suspension stiffness on vehicle axle flex.

The object of the invention is to provide a new type of vehicle suspension system destined for new vehicles, particularly for road and off-road ones, which also can be assembled in existing vehicles during overhauls, e.g. in tanks, and which improves substantially the shock absorption within the whole range of dynamical loads and vehicle weight variations.

The essence of the vehicle suspension system, according to the present invention, is that it comprises at least one flat or spatial four-link mechanism, three kinematic pairs of which are rotational ones, while the fourth one is either a rotational or a sliding one, and the two links of said mechanism are made in the form of eccentric and one link is made in the form of eccentric or slider, wherein one link of said mechanism is coupled with a vehicle wheel, another link of the mechanism is coupled with a spring, and the whole mechanism is fastened to a vehicle frame through yet another link, to obtain a non-linear dependence of deformation of the spring on an axle flex.

A good result is obtained when said suspension system, as four links of its mechanism, comprises a shaft fitted with an eccentric which is coupled rotationally with an intermediate eccentric, the latter being coupled rotationally with a disc, while the shaft and the disc pivot directly in a mechanism body. The body is fastened to a vehicle frame. The shaft, in turn, is coupled rigidly with a vehicle wheel arm, and the disc is coupled with one end of a spring, the other end of which is fastened to the body of the mechanism or directly to the vehicle frame. In this arrangement, the axes of rotation of all the kinematic pairs of the suspension mechanism are parallel to each other.

A good result is also obtained when the suspension system, as its four links, comprises a shaft fitted with an eccentric which is coupled rotationally with an intermediate eccentric which, in turn, is coupled rotationally with a disc, while the shaft and the disc pivot directly in a mechanism body, the latter being fastened to a vehicle frame. Besides, the disc is coupled rigidly with a vehicle wheel arm, and the shaft is coupled with one end of a spring the other end of which is fastened to the body or directly to the vehicle frame. In this arrangement the axes of rotation of all the kinematic pairs of the suspension mechanism are parallel to each other.

Amended sheet.2.

WO 01/03958

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#### What I claim is:

- 1. A vehicle suspension system comprising a spring and at least one flat or spatial four-link mechanism (K, M, W, D), at least three kinematic pairs of which are rotational ones, wherein one of the links of said mechanism is coupled with a vehicle wheel, another of said links is coupled with a spring (S), and the whole mechanism is fastened to a vehicle frame through yet another link of said mechanism, to obtain non-linear dependence of deformation of the spring on the vehicle wheel flex, characterized in that, three of said links are made in the form of an eccentric, whereby said four-link mechanism (K, M., W, D) comprises a shaft (W) fitted with an eccentric (MW), the latter being coupled rotationally with an intermediate eccentric (M), the latter being coupled rotationally with a disc (D), wherein the shaft (W) and the disc (D) pivot directly in a body (K).
- 2. A vehicle suspension system according to claim 1, characterized in that the axes of rotation of all the kinematic pairs of said suspension mechanism are parallel to each other.
  - 3. A vehicle suspension system according to claim 1, characterized in that the axes of rotation of all the kinematic pairs of said suspension mechanism intersect at a precisely one point P, to obtain a required position of the spring relative to the vehicle wheel.
- 4. A vehicle suspension system according to claim 2 or claim 3, characterized by said body (K) being fastened to a vehicle frame, and said shaft (W) being coupled rigidly with a wheel arm, and wherein the disc (D) is coupled with one end of the spring (S) the other end of which is fixed to the body (K) or directly to the vehicle frame.
  - 5. A vehicle suspension system according to claim 2 or claim 3, characterized by said body (K) being fastened to a vehicle frame, and said disc (D) being coupled rigidly with a wheel arm, and said shaft (W) being coupled with one end of a spring (S) the other end of which is fixed to the body (K) or directly to the vehicle frame.

---- Amended Sheet 1 (claims)

WO 01/03958

: PCT/PL 00/00030

- 6. A vehicle suspension system according to claim 2 or claim 3, characterized by said shaft (W) being fastened to a vehicle frame through the flange (Z), said intermediate eccentric (M) being coupled rigidly with a vehicle wheel arm (H), and said body (K) being coupled rigidly with one end of a spring (S) the other end of which is fixed to the shaft (W) or directly to the vehicle frame.
- 7. A vehicle suspension system according to claim 2 or claim 3, characterized by said body (K) being fastened to a vehicle frame, said shaft (W) being coupled rigidly with a vehicle wheel arm, and the intermediate eccentric (M) being coupled with one end of an U-shaped torsion bar the other end of which is fixed to the intermediate eccentric of an analogous mechanism of a suspension of the other wheel.
- 8. A vehicle suspension system comprising a spring and a least one flat or spatial four-link mechanism (K, M, W, D), three kinematic pairs of which are rotational ones and one of the links being made in the form of a slider such that the fourth kinematic pair is a sliding one, wherein one of the links of said mechanism is coupled with a vehicle wheel, another of said links is coupled with a spring (S), and the whole mechanism is fastened to a vehicle frame through yet another link of said mechanism, to obtain non-linear dependence of deformation of the spring on the vehicle wheel flex, characterized in that, two of said links are made in the form of an eccentric, whereby said four-link mechanism comprises a shaft (W) fitted with an eccentric (MW), the latter being coupled rotationally with an intermediate eccentric (M), the latter being coupled rotationally with a slider (D), wherein the shaft (W) pivots directly in a body (K) and the slider is slidingly fitted in the body (K).
- 9. A vehicle suspension system according to claim 8, characterized by a shaft (W) fitted with three eccentrics (MW1), (MW2) and (MW3), the latter being coupled rotationally with corresponding intermediate eccentrics (M1), (M2), and (M3), the latter being coupled rotationally with corresponding (D1), (D2) and (D3), wherein the sliders (D1), (D2) and (D3) are slidingly fitted in the body (K), said body (K) being fastened to a vehicle frame, the slider (D2) being coupled with a vehicle axle and the sliders (D1) and (D2) being coupled with a spring, which, in turn, is fastened to the vehicle frame.

Amended sheet 2 (claims) : -



(PCT Article 18 and Rules 43 and 44)

Applicant's or agent's file reference	FOR FURTHER see Notification of Transmittal of International Search Report (Form PCT/ISA/220) as well as, where applicable, item 5 below.			
International application No.	International filing date (day/month/year)	(Earliest) Priority Date (day/month/year)		
PCT/PL 00/00030	19/04/2000	12/07/1999		
Applicant				
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This International Search Report has be according to Article 18. A copy is being	een prepared by this International Searching Aut transmitted to the International Bureau.	hority and is transmitted to the applicant		
This International Search Report consis	sts of a total of3 sheets. by a copy of each prior art document cited in this	s report.		
Basis of the report     a. With regard to the language, the second content of the language.	ne international search was carried out on the ba	sis of the international application in the		
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2. Certain claims were fo	ound unsearchable (See Box I).			
3. Unity of Invention is in	acking (see Box II).			
4. With regard to the title,	•			
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5. With regard to the abstract,				
CC)	submitted by the applicant.			
the text has been estab	lished, according to Rule 38.2(b), by this Authori he date of mailing of this international search rep			
6. The figure of the drawings to be pu	iblished with the abstract is Figure No.	1		
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because the applicant f	ailed to suggest a figure.			
because this figure bett	er characterizes the invention.			



A. CLASSIFICATION OF SUBJECT MATTER IPC 7 B60G17/02 B600 B60G17/02 B60G11/00 B60G21/04 B60G21/055 According to International Patent Classification (IPC) or to both national classification and IPC **B. FIELDS SEARCHED** Minimum documentation searched (classification system followed by classification symbols) IPC 7 B60G Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched Electronic data base consulted during the international search (name of data base and, where practical, search terms used) EPO-Internal, PAJ C. DOCUMENTS CONSIDERED TO BE RELEVANT Citation of document, with indication, where appropriate, of the relevant passages Category ° Relevant to claim No. Α WO 96 11815 A (HOLT LAURENCE J) 1 25 April 1996 (1996-04-25) figures 8-19 US 1 991 911 A (RILEY, P.) Α 1 19 February 1935 (1935-02-19) figures 1,8 Α US 3 157 394 A (KELLEY, O.K.) 1 17 November 1964 (1964-11-17) figures 1-3,7,8 US 3 460 852 A (BENSON RICHARD J) 1 12 August 1969 (1969-08-12) figures Further documents are listed in the continuation of box C. Χ X Patent family members are listed in annex. Special categories of cited documents: "T" later document published after the international filing date or priority date and not in conflict with the application but "A" document defining the general state of the art which is not considered to be of particular relevance cited to understand the principle or theory underlying the earlier document but published on or after the international "X" document of particular relevance; the claimed invention filing date cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone "L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified) "Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such docudocument referring to an oral disclosure, use, exhibition or other means ments, such combination being obvious to a person skilled in the art. document published prior to the international filing date but later than the priority date claimed "&" document member of the same patent family Date of the actual completion of the international search Date of mailing of the international search report 28 August 2000 04/09/2000 Name and mailing address of the ISA Authorized officer European Patent Office, P.B. 5818 Patentlaan 2 NL – 2280 HV Rijswijk Tel. (+31–70) 340–2040, Tx. 31 651 epo nl, Fax: (+31–70) 340–3016 Tsitsilonis, L



Inter nal Application No L 00/00030

	ntinuation) DOCUMENTS CONSIDERED TO BE RELEVANT						
Category °	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.					
A	WO 94 11650 A (NAI NEWAY INC) 26 May 1994 (1994-05-26) figures 						
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n patent family members

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Patent docum cited in search		Publication date		atent family nember(s)	Publication date
WO 961181	5 A	25-04-1996	CA AU BR CN EP JP US	2117945 A 3602495 A 9506409 A 1136793 A 0730534 A 9507451 T 5839742 A	13-04-1996 06-05-1996 09-09-1997 27-11-1996 11-09-1996 29-07-1997 24-11-1998
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WO 01/03958 PCT/PL00/00030

#### Vehicle suspension system, particularly for road and off-road vehicles

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The present invention relates to a vehicle suspension system, particularly for road and off-road vehicles, such as trucks, buses and military vehicles, including tanks, and first of all for those vehicles whose weight and dynamical loads vary within a broad range during the operating process.

The main function of vehicle suspension is to reduce vibrations transferred to a vehicle body by vehicle wheels. The suspension is a set of elements connecting the vehicle wheels with the vehicle frame or body. Suspensions of automotive vehicles are fitted with steel springs such as leaf springs, coil springs, torsion bars, as well as solid rubber elements and pneumatic springs and hydro-pneumatic elements.

Leaf springs are made of elastic steel flat bars. The leaf spring, supported in the middle and loaded on both ends, is subject to deformation and simultaneously works against the forces of elasticity.

Coil springs are made of steel spring wire. They are lighter and easier to assemble than leaf springs but unable to transfer side forces, hence additional elements are necessary to hold the vehicle axle.

Torsion bars are steel springs made in the form of rod, tube or flat bar pack, one end of which is anchored e.g. in a vehicle frame while the other one is twisted by an arm of a vehicle wheel.

Pneumatic springs are built in the form of two or three-fold bellow manufactured of synthetic rubber reinforced with cord plait and tightened in metallic holders. Pneumatic springs work utilizing pressure of compressed air contained therein. They are used in buses and trucks as well as in off road vehicles. There are also hydro-pneumatic suspensions, in which the elastic medium is a compressed gas contained in a chamber.

Further compression of the gas results from the action of a piston, which follows the movement of a vehicle wheel.

A vehicle suspension, according to the present invention, is a purely mechanical device. It features a compact and robust structure and it uses only standard springs, while it provides a characteristic, which betters that of hydro-pneumatic suspensions. Moreover, the construction of the suspension, according to the invention, enables its characteristic to be freely chosen through the choice of the geometric parameters of the mechanisms comprised therein.

The manufacturing technology of the suspension according to the invention is simple and inexpensive. Moreover, the suspension provides the possibility of the relative position between elements connecting the suspension unit with vehicle wheels and a spring to be freely adjusted.

The invention solves the problem of constructing a vehicle suspension of non-linear characteristic using springs of linear characteristic. By non-linear characteristic is meant non-linear and differentiable dependence of suspension stiffness on vehicle axle flex.

The object of the invention is to provide a new type of vehicle suspension system destined for new vehicles, particularly for road and off-road ones, which also can be assembled in existing vehicles during overhauls, e.g. in tanks, and which improves substantially the shock absorption within the whole range of dynamical loads and vehicle weight variations.

The essence of the vehicle suspension system, according to the present invention, is that it comprises at least one flat or spatial four-link mechanism, three kinematic pairs of which are rotational ones, while the fourth one is either a rotational or a sliding one, and the two links of said mechanism are made in the form of eccentric and one link is made in the form of eccentric or slider, wherein one link of said mechanism is coupled with a vehicle wheel, another link of the mechanism is coupled with a spring, and the whole mechanism is fastened to a vehicle frame through yet another link, to obtain a non-linear dependence of deformation of the spring on an axle flex.

A good result is obtained when said suspension system, as four links of its mechanism, comprises a shaft fitted with an eccentric which is coupled rotationally with an intermediate eccentric, the latter being coupled rotationally with a disc, while the shaft and the disc pivot directly in a mechanism body. The body is fastened to a vehicle frame. The shaft, in turn, is coupled rigidly with a vehicle wheel arm, and the disc is coupled with one end of a spring, the other end of which is fastened to the body of the mechanism or directly to the vehicle frame.

In this arrangement, the axes of rotation of all the kinematic pairs of the suspension mechanism are parallel to each other.

A good result is also obtained when the suspension system, as its four links, comprises a shaft fitted with an eccentric which is coupled rotationally with an intermediate eccentric which, in turn, is coupled rotationally with a disc, while the shaft and the disc pivot directly in a mechanism body, the latter being fastened to a vehicle frame. Besides, the disc is coupled rigidly with a vehicle wheel arm, and the shaft is coupled with one end of a spring the other end of which is fastened to the body or directly to the vehicle frame. In this arrangement the axes of rotation of all the kinematic pairs of the suspension mechanism are parallel to each other.

A good result is also obtained when the suspension system comprises a shaft fitted with a flange and an eccentric, the latter being coupled rotationally with an intermediate eccentric which, in turn, is coupled rotationally with a disc, while the shaft and the disc pivot directly in a mechanism body. The shaft is fastened to a vehicle frame with the help of the flange, while the intermediate eccentric is coupled rigidly with a vehicle wheel arm, and the body is coupled rigidly with one end of a spring the other end of which is fastened to the shaft or directly to the vehicle frame.

In this arrangement the axes of rotation of all the kinematic pairs of the suspension mechanism are parallel to each other.

A good result is also obtained when the suspension system comprises two flat four-link mechanisms and a steel spring in the form of U-shaped torsion bar, wherein each mechanism, as its four links, comprises a shaft fitted with an eccentric which is coupled rotationally with an intermediate eccentric, the latter in turn being coupled rotationally with a disc, whereas the shaft and the disc pivot directly in a mechanism body.

The body of each mechanism is fastened to a vehicle frame, and the shaft is coupled rigidly with a vehicle wheel arm, while the intermediate eccentric is coupled with one end of the U-shaped torsion bar the other end of which is fastened to the intermediate eccentric of the analogous mechanism of the suspension of the other wheel.

In this arrangement the axes of rotation of all the kinematic pairs of each suspension mechanism are parallel to each other.

A good result is also obtained when the suspension system, as four links of its mechanism, comprises a shaft fitted with an eccentric which is coupled rotationally with an intermediate eccentric, the latter in turn being coupled rotationally with a disc, whereas the shaft and the disc pivot directly in a mechanism body. The body is fastened to a vehicle frame and the shaft is coupled rigidly with a vehicle wheel arm, while the disc is coupled with one end of a spring the other end of which is fastened to the mechanism body or directly to the vehicle frame.

The suspension is in accordance with the invention provided that the axes of rotation of all the kinematic pairs of the suspension mechanism intersect at a precisely one point P.

A good result is also obtained when the suspension system, as four links of its mechanism, comprises a shaft fitted with an eccentric which is coupled rotationally with an intermediate eccentric which, in turn, is coupled rotationally with a disc. The shaft and the disc pivot directly in a mechanism body, which is fastened to a vehicle frame.

Besides, the disc is coupled rigidly with a vehicle wheel arm, and the shaft is coupled with one end of a spring the other one of which is fastened to the mechanism body or directly to the vehicle frame.

The suspension is in accordance with the invention provided the axes of rotation of all the kinematic pairs of said suspension mechanism intersect at a precisely one point P.

A good result is also obtained when the suspension system, according to the invention, comprises a shaft fitted with a flange and an eccentric, which is coupled rotationally with an intermediate eccentric, which in turn is coupled rotationally with a disc. The shaft is fastened to a vehicle frame with the help of the flange whereas the intermediate eccentric is coupled rigidly with a vehicle wheel arm. The mechanism's body is coupled rigidly with one end of a spring the other end of which is fastened to the shaft or directly to the vehicle frame.

The suspension is in accordance with the invention provided the axes of rotation of all the kinematic pairs of said suspension mechanism intersect at a precisely one point P.

A good result is also obtained when the suspension system, according to the invention, comprises two four-link spatial mechanisms and a spring in the form of U-shaped torsion bar, whereas each mechanism, as its four links, comprises a shaft fitted with an eccentric which is coupled rotationally with an intermediate eccentric, the latter, in turn, is coupled rotationally with a disc, whereas the shaft and the disc pivot directly in a body. Additionally, the body of each mechanism is fastened to a vehicle frame, and the shaft is coupled with a vehicle wheel arm, while the intermediate eccentric is coupled with one end of the U-shaped torsion bar the other end of which is fastened to the intermediate eccentric of the analogous mechanism of the suspension of the other wheel.

The suspension is in accordance with the invention provided that the axes of rotation of all the kinematic pairs of each of the suspension mechanisms intersect at a precisely one point P.

A good result is also obtained when the suspension system, according to the invention, comprises a shaft fitted with three eccentrics which are coupled rotationally with corresponding intermediate eccentrics which, in turn, are coupled rotationally with corresponding sliders, whereas the shaft pivots directly in a body and the sliders are sliding fitted in the mechanism body, whereas one of the sliders is coupled with a vehicle axle while the two others are coupled with a spring, the latter being fastened to a vehicle frame. The body is fastened to the vehicle frame.

The object of the invention is shown in the accompanying drawings, where Fig. 1 shows a vehicle suspension system provided with a torsion bar, intended for fastening to a vehicle frame

with the help of a mechanism body, and the suspension mechanism shaft coupled with a vehicle wheel arm; Fig. 2 shows a vehicle suspension system provided with a torsion bar and a disc coupled with a wheel arm, which is fit for fastening to a vehicle body with the help of a mechanism body; Fig. 3 shows a vehicle suspension system provided with a coil spring and an intermediate eccentric coupled with a vehicle wheel arm, which is fit for fastening to a vehicle body through the shaft equipped with a flange;

Fig. 4 shows a vehicle suspension system equipped with a U-shaped torsion bar coupling two suspension mechanisms with the help of their intermediate eccentrics, Fig. 5 shows a vehicle suspension system in which the axes of rotation and the axes of symmetry of all the suspension mechanism links intersect at a precisely one point P; Fig. 6 shows a vehicle suspension system of the Mc Pherson type; Fig. 7 shows a vehicle suspension system equipped with a leaf spring; Fig. 8 provides an example of a suspension answer force F as a function of a vehicle wheel flex x.

#### Example 1

The suspension unit comprises a shaft (W) fitted with an eccentric bore chamber (MW). In the eccentric bore chamber (MW) of the shaft (W) pivots a pivot (C) of an intermediate eccentric (M), the other end of which pivots inside of the eccentric bore chamber of a disc (D). The shaft (W) and the disc (D) pivot directly in a body (K). An arm (H) is fastened to the pivot of the shaft (W). One end of a torsion bar (S) is coupled rigidly with the disc (D), and the other one is anchored in a vehicle frame. The entire suspension unit is fastened to the vehicle frame with the help of a flange (Z) at the body (K).

In this arrangement, the axis OW of rotation of the shaft (W) relative to the body (K), the axis OD of rotation of the disc (D) relative to the body (K), the symmetry axis OC of the eccentric (MW) at the shaft (W) and the overlapping axis of rotation of the shaft (W) relative to the intermediate eccentric (M), and the symmetry axis OM of the intermediate eccentric (M), and the overlapping axis of rotation of the intermediate eccentric (M) relative to the disc (D) are all parallel to each other.

Owing to said arrangement, the suspension features a strongly progressive characteristic, much better than that of the hydro-pneumatic ones. Its characteristic is differentiable in contradistinction to other progressive suspensions of jump characteristic fitted with a few in turns actuating steel springs.

The suspension gives the possibility to choose freely the suspension characteristics, including its progressiveness, through the selection of geometric parameters of its mechanism.

what is an additional advantage over hydro-pneumatic suspension whose characteristic is determined by the gas being used. The suspension features a combination of small deformations of the spring with large wheel flex, which lengthens spring's life.

#### Example 2

The suspension unit comprises a shaft (W) fitted with an eccentric (MW), said eccentric (MW) being pivoted in an eccentric bore chamber of an intermediate eccentric (M), whereas the eccentric (M) pivots inside of an eccentric bore chamber of a disc (D). The shaft and the disc pivot in a body (K).

A torsion bar (S) is fastened to the shaft (W), and an arm (H) is coupled with the disc (D). The whole suspension unit is fixed to a vehicle frame with the help of a flange (Z) at the body (K).

In this arrangement, the axis OW of rotation of the shaft (W) relative to the body (K), the axis OD of rotation of the disc (D) relative to the body (K), the symmetry axis OC of the eccentric (MW) at the shaft (W) and the overlapping axis of rotation of the shaft (W) relative to the intermediate eccentric (M), and the symmetry axis OM of the intermediate eccentric (M) and the overlapping axis of rotation of the intermediate eccentric (M) relative to the disc (D) are all parallel to each other.

The suspension features a very strongly progressive characteristic, since to a relatively small vehicle wheel flex there corespondes a relatively large angle of rotation of the shaft (W), and hence a large torsion of the torsion bar, in contradistinction to the suspension described in Example 1. During overhauls, the suspension may be assembled in existing vehicles, e.g. in tanks.

#### Example 3

The suspension system comprises a shaft (W) fitted with an eccentric (MW), wherein the eccentric (MW) pivots in an eccentric bore chamber of an intermediate eccentric (M), and the eccentric (M) pivots inside of an eccentric bore chamber of the disc (D). The disc (D) pivots directly in a body (K) and the body (K) is coupled rotationally with the main pivot of the shaft (W). An arm (H) is fastened to a pivot (C) of the intermediate eccentric (M). The body (K) is fitted with a bracket (WS) on which the coil spring (S) is being supported, the other end of which rests on a vehicle frame. The whole suspension unit is fastened to a vehicle body with the help of a flange (Z) at the shaft (W).

In this arrangement the axis OW of rotation of the shaft (W) relative to the body (K), the axis OD of rotation of the disc (D) relative to the body (K), the symmetry axis OC of the

eccentric (MW) at the shaft (W) and the overlapping axis of rotation of the shaft (W) relative to the intermediate eccentric (M), and the symmetry axis OM of the intermediate eccentric (M) and the overlapping axis of rotation of the intermediate eccentric (M) relative to the disc (D) must be parallel to each other.

The described suspension mounting to the vehicle frame makes it easier to use a coil spring, which is the most widespread kind of steel spring. The suspension may be assembled in existing vehicles, e.g. in tanks, during overhauls.

#### Example 4

An arrangement described in this example is a compound suspension system for two wheels on common axle. It comprises two four-link mechanisms and a spring in the form of U-shaped torsion bar, which works simultaneously as a stabilizer. The torsion bar is coupled rotationally with a vehicle frame through clamping rings (O) at the base of the letter U.

The suspension mechanism, as its four links, comprises a shaft (W) fitted with an eccentric (MW) which is coupled rotationally with an intermediate eccentric (M) which, in turn, is coupled rotationally with a disc (D). The shaft (W) and the disc (D) pivot directly in a body (K). The body (K) of each mechanism is fastened to a vehicle frame, the shaft (W) is coupled rigidly with an arm (H), and the intermediate eccentric (M) is coupled with one end of the U-shaped torsion bar the other end of which is fastened to the intermediate eccentric of the analogous mechanism of the other wheel suspension. In both mechanisms, the axis OW of rotation of the shaft (W) relative to the body (K), the axis OD of rotation of the disc (D) relative to the body (K), the symmetry axis OC of the eccentric (MW) at the shaft (W) and the overlapping axis of rotation of the intermediate eccentric (M) relative to the shaft (W), and the symmetry axis OM of the intermediate eccentric (M) and the overlapping axis of rotation of the intermediate eccentric (M) and the overlapping axis of rotation of the intermediate eccentric (M) are all parallel to each other.

Owing to the application of an U-shaped torsion bar both ends of which are coupled with elements of the suspension mechanisms executing both the rotary and the planetary motion, the bar is subject to complex stresses depending on the wheels position. In the case of identical flex of both the wheels, the arms of the U-shaped torsion bar are being twisted and simultaneously slightly expanded. In the case of various flexes of the wheels, the part of the torsion bar constituting the base of the letter (U) additionally is being twisted. Thus, the torsion bar plays the role of both the main spring for two wheels and the stabilizer.

The suspension, similarly to those described above, features a strongly non-linear characteristic, also for the stabilizer.

#### Example 5

The suspension system comprises a shaft (W) fitted with an eccentric (MW), whereas the eccentric (MW) pivots inside of an eccentric bore chamber of an intermediate eccentric (M), which in turn pivots inside of an eccentric bore chamber of a disc (D). The shaft (W) and the disc (D) pivot directly in a body (K). An arm (H) is fastened to the shaft (W).

A torsion bar (S) is coupled with the disc (D), and the whole suspension unit is fixed to a vehicle frame with the help of a flange (Z) at the shaft (W).

The axes of rotation of all the kinematic pairs of the mechanism of this unit suspension intersect at a precisely one point P. In particular, the axis of rotation of the shaft (W) and the axis of rotation of the disc (D) (the latter overlapping the symmetry axis of the torsion bar) intersect at an angle A.

This arrangement gives the possibility to choose freely the angle A within the range of 0-90°, which gives the possibility of a position of the spring relative to the wheel to be conveniently chosen. In particular, in the case the angle A equals 90°, one obtains a suspension with a trailing arm and a longitudinal torsion bar.

The suspension features a strongly non-linear characteristic, which can be freely shaped through an appropriate choice of the geometric parameters of its mechanism.

#### Example 6

The Mc Pherson-type suspension system comprises a shaft (W) fitted with an eccentric (MW), an intermediate eccentric (M), a disc (D), and a body (K). The shaft (W) and the disc (D) pivot directly in the body (K), while the intermediate eccentric pivots on the shaft eccentric (MW). A radius arm (H) is fastened to the shaft (W), and a bracket (T) supporting a coil spring (S) is fastened to the disc (D).

The axes of rotation of all the kinematic pairs of the suspension mechanism are parallel to each other.

The suspension has a non-linear progressive characteristic and compact structure, typical for suspensions of the McPherson type.

#### Example 7

A suspension system fitted with a leaf spring has a shaft (W) fitted with three eccentrics (MW1, MW2, MW3), three intermediate eccentrics (M1, M2, M3), and three sliders (D1, D2, D3), whereas the slider set (D1, D2, D3) and the intermediate eccentrics (M1, M2, M3) mate the shaft eccentrics (MW1, MW2, MW3) respectively. The shaft (W) pivots in a body (K), and the sliders (D1, D2, D3) are sliding fitted in the body (K). The central slider (D2) is coupled with a

vehicle axis, and the leaf spring is fastened to the outer sliders (D1) and (D3). Eccentricity ratios of the eccentrics (MW1) and (MW3) are equal one to the other.

Moreover, the eccentricity ratio of each shaft eccentric (MW1, MW2, MW3) equals the eccentricity ratio of the intermediate eccentric (M1, M2, M3) which it mate.

The shaft eccentrics (MW1) and (MW3) are both rotated by certain angle A relative to the shaft eccentric (MW2). The proper choice of the angle A provides a non-linear characteristic of the suspension of the required progressiveness ratio.

The suspension maintains an important advantage of the leaf spring i.e. its capability to hold alone the vehicle axle.

A common distinctive feature of all the suspension systems described above is a non-linear and differentiable characteristic which provides an extraordinary adaptability of the suspension stiffness to variable static and dynamic loads, thus providing a smooth and stable ride within the whole range of the vehicle loads.

#### What I claim is:

- 1. A vehicle suspension system, particularly for road and off-road ones, comprising springs, distinguished for the fact that the suspension system comprises at least one flat or spatial four-link mechanism (K), (M), (W) and (D), three kinematic pairs of which are rotational ones while the fourth one is either a rotational or a sliding one, wherein two links are made in the form of eccentric and one link is made in the form of eccentric or slider, wherein one of the links of said mechanism is coupled with a vehicle wheel, the other one is coupled with a spring (S), and the whole mechanism is fastened to a vehicle frame through yet another link of said mechanism, to obtain non-linear dependence of deformation of the spring on the vehicle wheel flex.
- 2. A vehicle suspension system according to claim l, distinguished for the fact that the suspension mechanism, as its four links, comprises a shaft (W) fitted with an eccentric (MW), the latter being coupled rotationally with an intermediate eccentric (M), the latter being coupled rotationally with a disc (D), wherein the shaft (W) and the disc (D) pivot directly in a body (K), said body (K) being fastened to a vehicle frame, and said shaft (W) being coupled rigidly with a wheel arm, and wherein the disc (D) is coupled with one end of the spring (S) the other end of which is fixed to the body (K) or directly to the vehicle frame, assuming the axes of rotation of all the kinematic pairs of said suspension mechanism are parallel to each other.
- 3. A vehicle suspension system according to claim 1, distinguished for the fact that the suspension mechanism, as its four links, comprises a shaft (W) fitted with an eccentric (MW), the latter being coupled rotationally with an intermediate eccentric (M), the latter being coupled rotationally with a disc (D), wherein the shaft (W) and the disc (D) pivot directly in a body (K), said disc (D) being coupled rigidly with a wheel arm, and said shaft (W) being coupled with one end of a spring (S) the other end of which is fixed to the body (K) or directly to a vehicle frame, assuming the axes of rotation of all the kinematic pairs of said suspension mechanism are parallel to each other.
- 4. A vehicle suspension system according to claim 1, distinguished for the fact that the suspension mechanism contains a shaft (W) fitted with a flange (Z) and an eccentric (MW), the latter being coupled rotationally with an intermediate eccentric (M), the latter being coupled rotationally with a disc (D), wherein the shaft (W) and the disc (D) pivot in a body (K), said

shaft (W) being fastened to a vehicle frame through the flange (Z), said intermediate eccentric (M) being coupled rigidly with a vehicle wheel arm (H), and said body (K) being coupled rigidly with one end of a spring (S) the other end of which is fixed to the shaft (W) or directly to the vehicle frame, assuming the axes of rotation of all the kinematic pairs of the suspension mechanism are parallel to each other.

- 5. A vehicle suspension system according to claim 1, distinguished for the fact that the suspension mechanism, as its four links, comprises a shaft (W) fitted with an eccentric (MW), the latter being coupled rotationally with an intermediate eccentric (M), the latter being coupled rotationally with a disc (D), wherein the shaft (W) and the disc (D) pivot directly in a body (K), said body (K) being fastened to a vehicle frame, said shaft (W) being coupled rigidly with a vehicle wheel arm, and the intermediate eccentric (M) being coupled with one end of an U-shaped torsion bar the other end of which is fixed to the intermediate eccentric of an analogous mechanism of a suspension of the other wheel, assuming the axes of rotation of all the kinematic pairs of the suspension mechanism are parallel to each other.
- 6. A vehicle suspension system according to claim 1, distinguished for the fact that the suspension mechanism, as its four links, comprises a shaft (W) fitted with an eccentric (MW), the latter being coupled rotationally with and intermediate eccentric (M), the latter being coupled rotationally with a disc (D), wherein the shaft (W) and the disc (D) pivot directly in a body (K), said body (K) being fastened to a vehicle frame, said shaft (W) being coupled rigidly with a wheel arm, and said disc being coupled with one end of a spring (S) the other end of which is fixed to the body (K) or directly to the vehicle frame, assuming the axes of rotation of all the kinematic pairs of said suspension mechanism intersect at a precisely one point P, to obtain a required position of the spring relative to the vehicle wheel.
- 7. A vehicle suspension system according to claim 1, distinguished for the fact that the suspension mechanism, as its four links, comprises a shaft (W) fitted with an eccentric (MW), the latter being coupled rotationally with an intermediate eccentric (M), the latter being coupled rotationally with a disc (D), wherein the shaft (W) and the disc (D) pivot directly in a body (K), said disc (D) being coupled rigidly with a wheel arm, said shaft (W) being coupled with one end of a spring (S) the other end of which is fastened to the body (K) or directly to a vehicle frame, assuming the axes of rotation of all the kinematic pairs of said suspension mechanism intersect

at a precisely one point P, to obtain a required position of the spring relative to the vehicle wheel.

- 8. A vehicle suspension system according to claim 1, distinguished for the fact that the suspension mechanism comprises a shaft (W) fitted with a flange (Z) and an eccentric (MW), the latter being coupled rotationally with an intermediate eccentric (M), the latter being coupled rotationally with a disc (D), wherein the shaft (W) and the disc (D) pivot in a body (K), said shaft (W) being fastened to a vehicle frame with the help of the flange (Z), said intermediate eccentric (M) being coupled rigidly with a wheel arm, and said body (K) being coupled rigidly with one end of a spring (S) the other end of which is fixed to the shaft (W) or directly to the vehicle frame, assuming the axes of rotation of all the kinematic pairs of said suspension mechanism intersect at a precisely one point P, to obtain a required position of the spring relative to the vehicle wheel.
- 9. A vehicle suspension system according to claim 1, distinguished for the fact that the suspension mechanism, as its four links, comprises a shaft (W) fitted with an eccentric (MW), the latter being coupled rotationally with an intermediate eccentric (M), the latter being coupled rotationally with a disc (D), wherein the shaft (W) and the disc (D) pivot directly in a body (K), said body (K) being fastened to a vehicle frame, said shaft (W) being coupled rigidly with a vehicle wheel arm and said intermediate eccentric (M) being coupled with one end of an U-shaped torsion bar the other end of which is fixed to the intermediate eccentric of an analogous mechanism of a suspension of the other wheel, assuming the axes of rotation of all the kinematic pairs of said suspension mechanism intersect at a precisely one point P, to obtain a required position of the spring relative to the vehicle wheel.
- 10. A vehicle suspension system according to claim 1, distinguished for the fact that the suspension mechanism comprises a shaft (W) fitted with three eccentrics (MW1), (MW2) and (MW3), the latter being coupled rotationally with corresponding intermediate eccentrics (M1), (M2) and (M3), the latter being coupled rotationally with corresponding sliders (D1), (D2) and (D3), wherein the shaft (W) pivots directly in a body (K), and the sliders (D1), (D2) and (D3) are sliding fitted in the body (K), said body (K) being fastened to a vehicle frame, the slider (D2) being coupled with a vehicle axle and the sliders (D1) and (D3) being coupled with a

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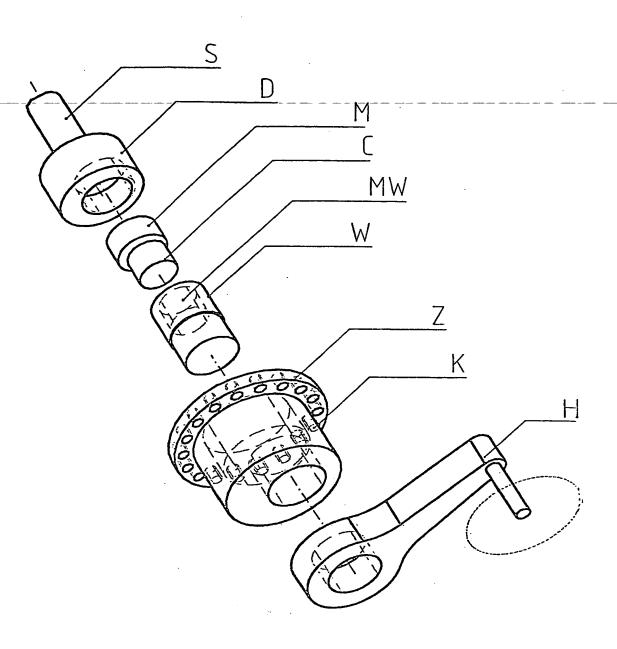


Fig. 1

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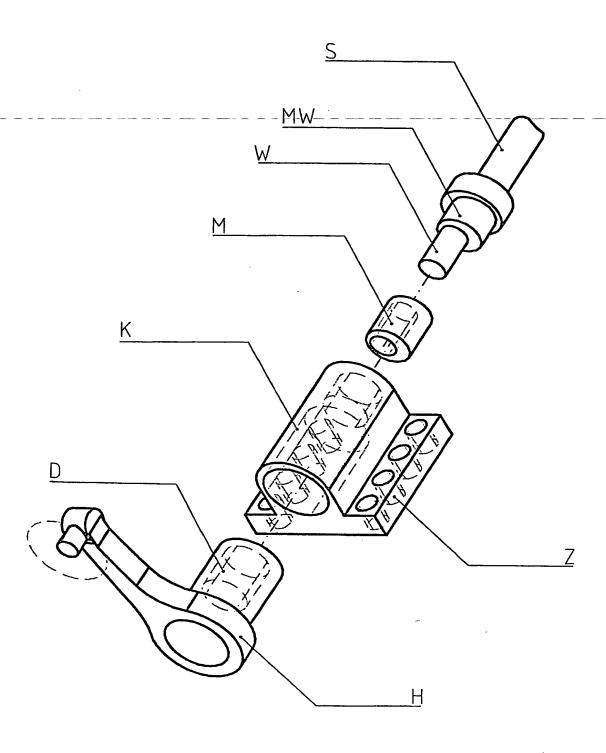


Fig. 2

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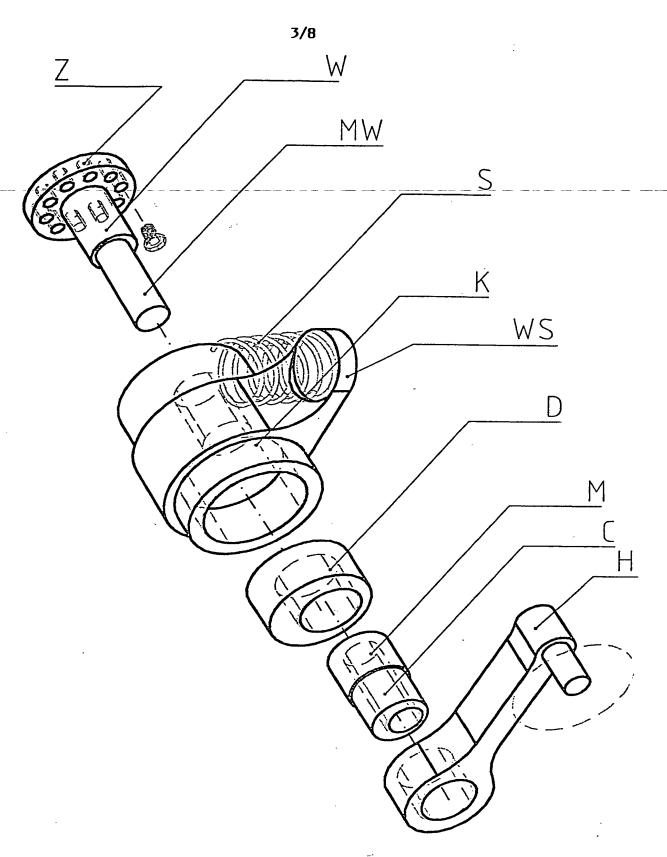


Fig. 3

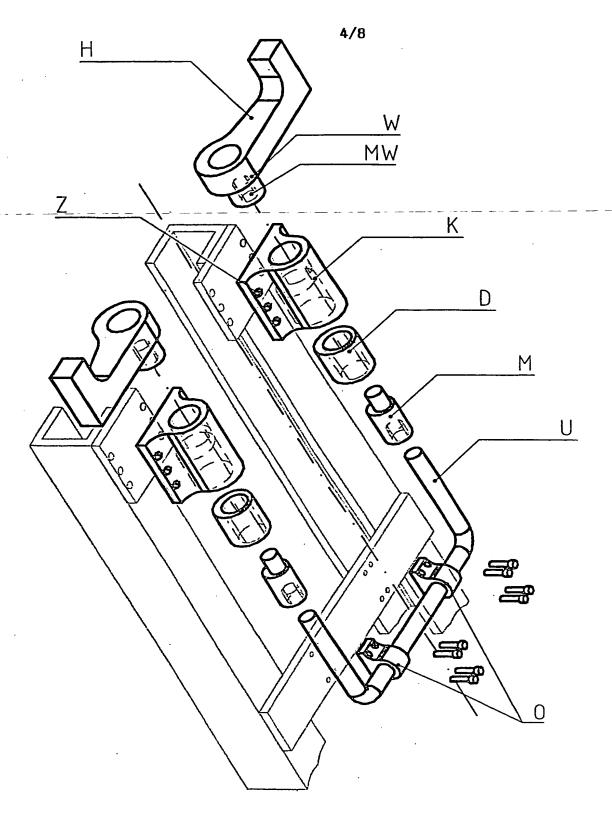


Fig. 4

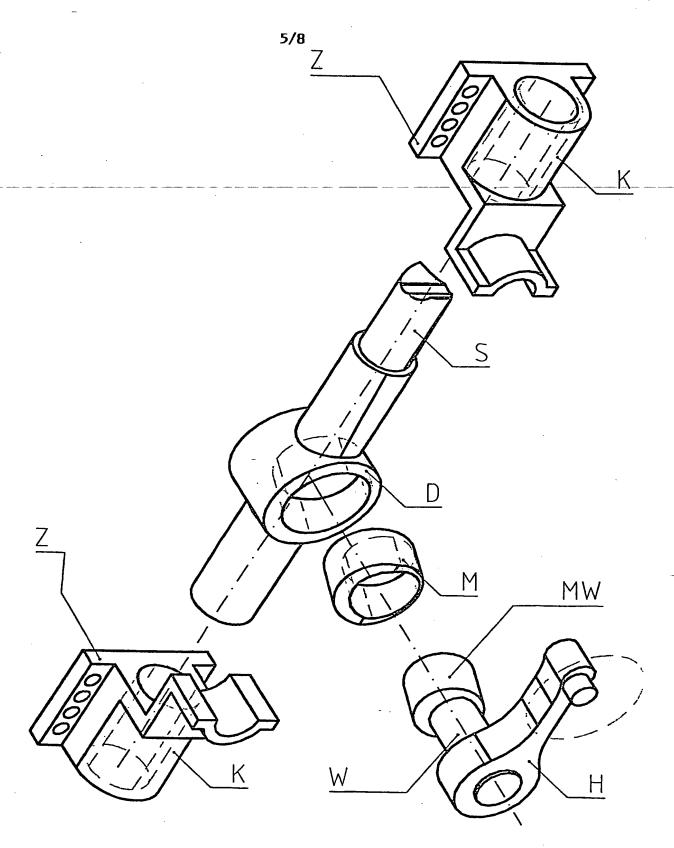


Fig. 5

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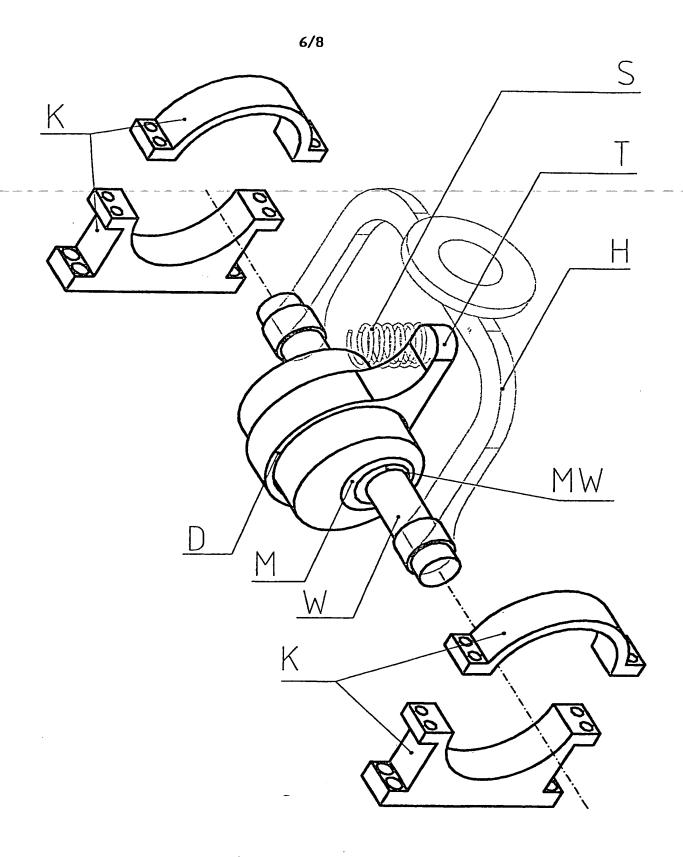


Fig. 6

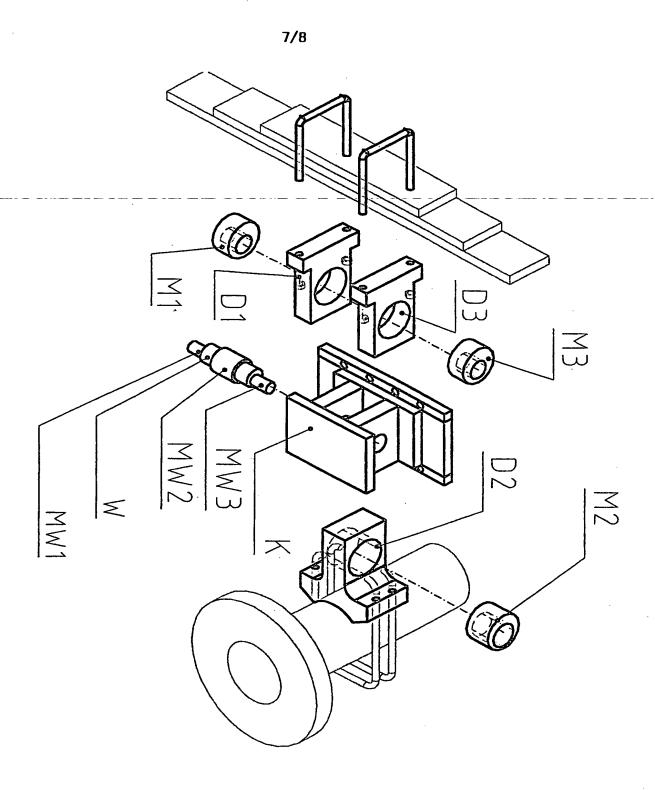


Fig. 7

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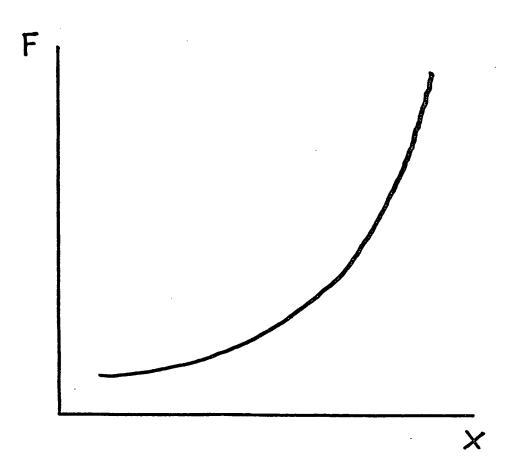


Fig.8

PCT/PL 00/00030 A. CLASSIFICATION OF SUBJECT MATTER IPC 7 B60G17/02 B60G B60G11/00 B60G21/04 B60G21/055 According to International Patent Classification (IPC) or to both national classification and IPC B. FIELDS SEARCHED Minimum documentation searched (classification system followed by classification symbols) IPC 7 B60G Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched Electronic data base consulted during the international search (name of data base and, where practical, search terms used) EPO-Internal, PAJ C. DOCUMENTS CONSIDERED TO BE RELEVANT Citation of document, with indication, where appropriate, of the relevant passages Category ° Relevant to claim No. Α WO 96 11815 A (HOLT LAURENCE J) 1 25 April 1996 (1996-04-25) figures 8-19 US 1 991 911 A (RILEY, P.) 1 19 February 1935 (1935-02-19) figures 1,8 Α US 3 157 394 A (KELLEY, O.K.) 1 17 November 1964 (1964-11-17) figures 1-3,7,8 Α US 3 460 852 A (BENSON RICHARD J) 1 12 August 1969 (1969-08-12) figures -/--X Further documents are listed in the continuation of box C. X Patent family members are listed in annex. Special categories of cited documents: "T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the "A" document defining the general state of the art which is not considered to be of particular relevance invention earlier document but published on or after the international "X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to filing date "L" document which may throw doubts on priority claim(s) or involve an inventive step when the document is taken alone which is cited to establish the publication date of another citation or other special reason (as specified) "Y" document of particular relevance; the claimed invention occurrent of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled "O" document referring to an oral disclosure, use, exhibition or other means document published prior to the international filing date but in the art. later than the priority date claimed "&" document member of the same patent family Date of the actual completion of the international search Date of mailing of the international search report 28 August 2000 04/09/2000 Name and mailing address of the ISA Authorized officer European Patent Office, P.B. 5818 Patentiaan 2

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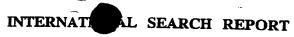
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